

Introduction to Simon-Smith min-max theory

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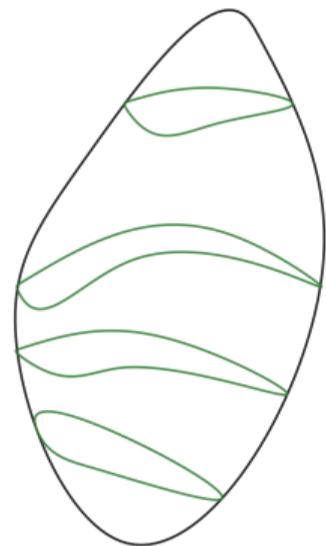
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Apart from minimal constructions, min-max arguments have been used in other contexts, like the proof of the **Willmore conjecture** by **Marques** and **Neves**, constructions of CMC and PMC surfaces, free boundary and capillary problems...

An intuitive idea of Birkhoff's theorem

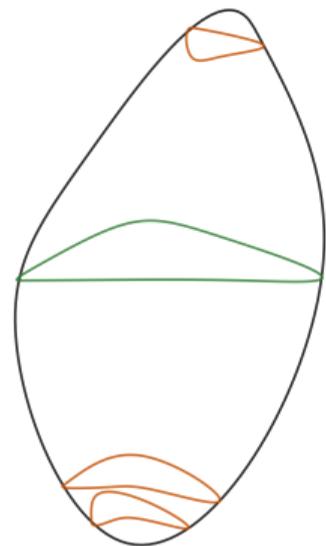
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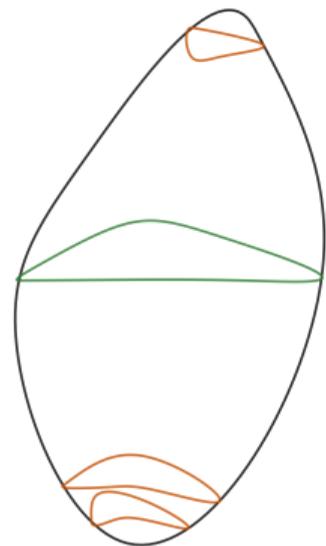


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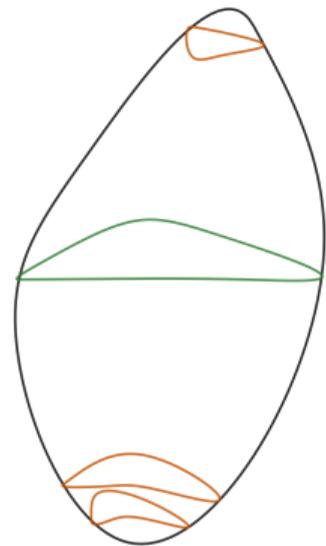
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We expect the length of Γ to satisfy

$$\text{Len}(\Gamma) = \min_{\{\tilde{\gamma}_t\} \in \Lambda} \max_t \text{Len}(\tilde{\gamma}_t),$$

where Λ is the set of all deformations of γ_t .



Colding, T. H., De Lellis, M. *The min–max construction of minimal surfaces.*



Simon, L. *Introduction to Geometric Measure Theory.*



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- 2 An (unfortunately irreducible) introduction to varifolds
- 3 Finding stationary varifolds
- 4 Regularity analysis of limit varifolds
 - Theorem 1: GRP implies minimality
 - Theorem 2: Existence of a.m. min-max sequence
 - Theorem 3: a.m. min-max sequence has GRP
- 5 Generalizations of the main Theorem

A family $\{\Sigma_t\}_{t \in [0,1]}$, $\Sigma_t \subset M$, is a **generalized family of surfaces (GFS)** if:

- Σ_t is a surface except for a **finite set** $t \in \mathcal{T} \subset [0, 1]$.
- There exists a **finite set** $\mathcal{P} \subset M$ such that $\Sigma_t \setminus \mathcal{P}$ is a surface for all $t \in \mathcal{T}$.
- $t \mapsto \mathcal{H}^2(\Sigma_t)$ is continuous.
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A collection of GFS's Λ is a **saturated set** if it is closed under the previous operation.

Inf max and minimizing sequences

Given $\{\Sigma_t\} \in \Lambda$, we define:

$$\mathcal{F}(\{\Sigma_t\}) := \max_{t \in [0,1]} \mathcal{H}^2(\Sigma_t)$$

$$m_0(\Lambda) := \inf_{\Lambda} \mathcal{F} = \inf_{\{\Sigma_t\} \in \Lambda} \max_{t \in [0,1]} \mathcal{H}^2(\Sigma_t)$$

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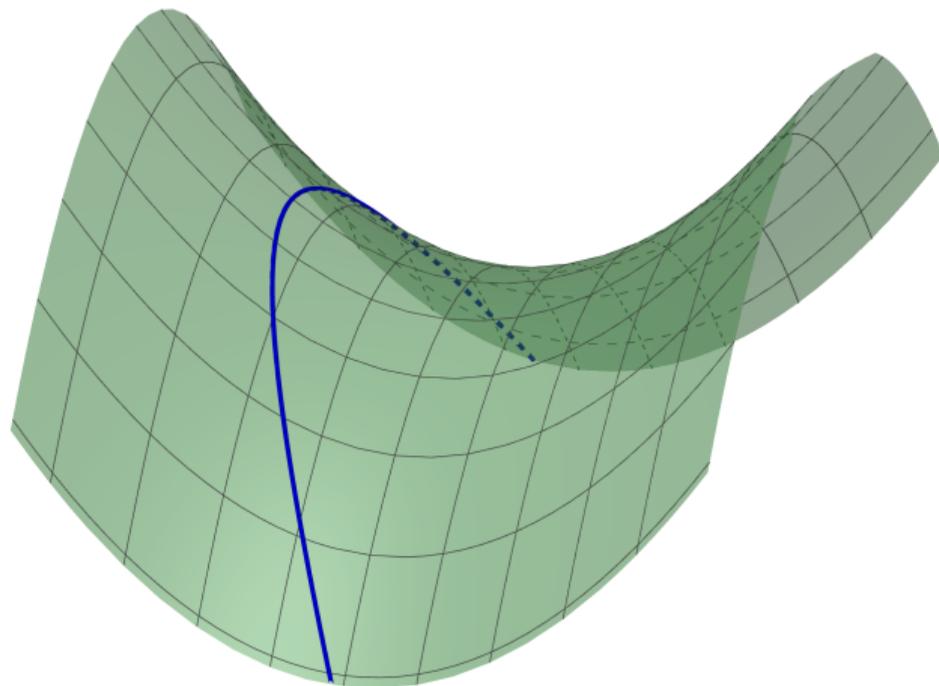
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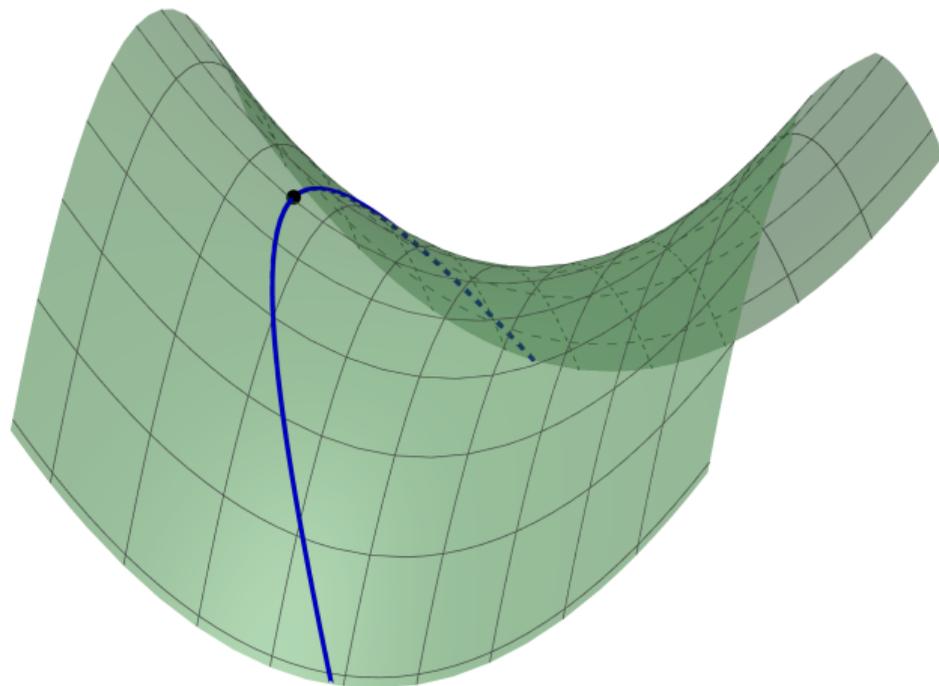
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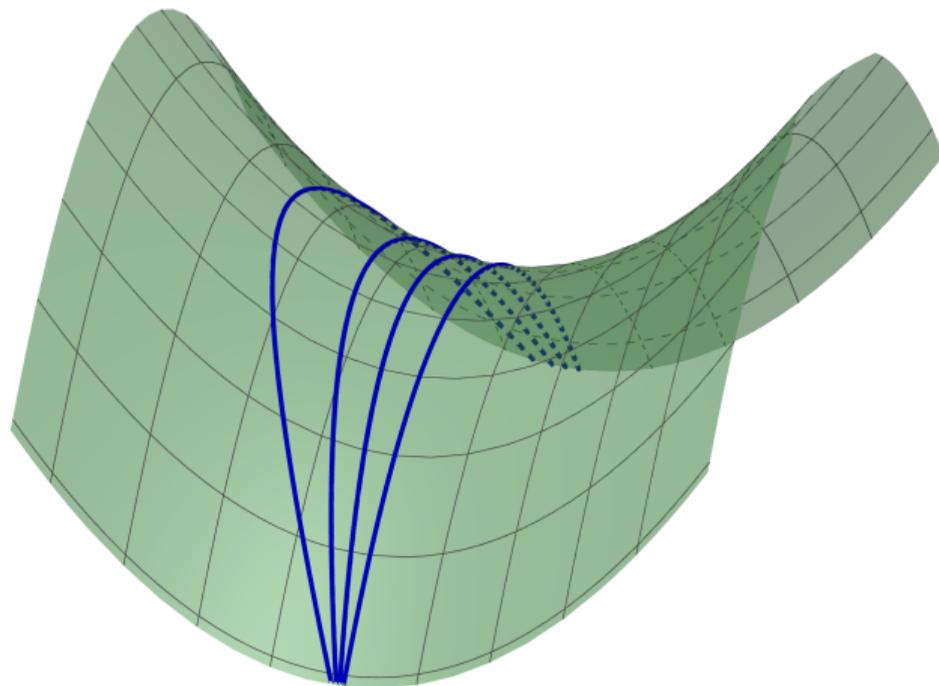
A sequence $\{\Sigma_t\}^n$ is **minimizing** if $\mathcal{F}(\{\Sigma_t\}^n) \rightarrow m_0(\Lambda)$.

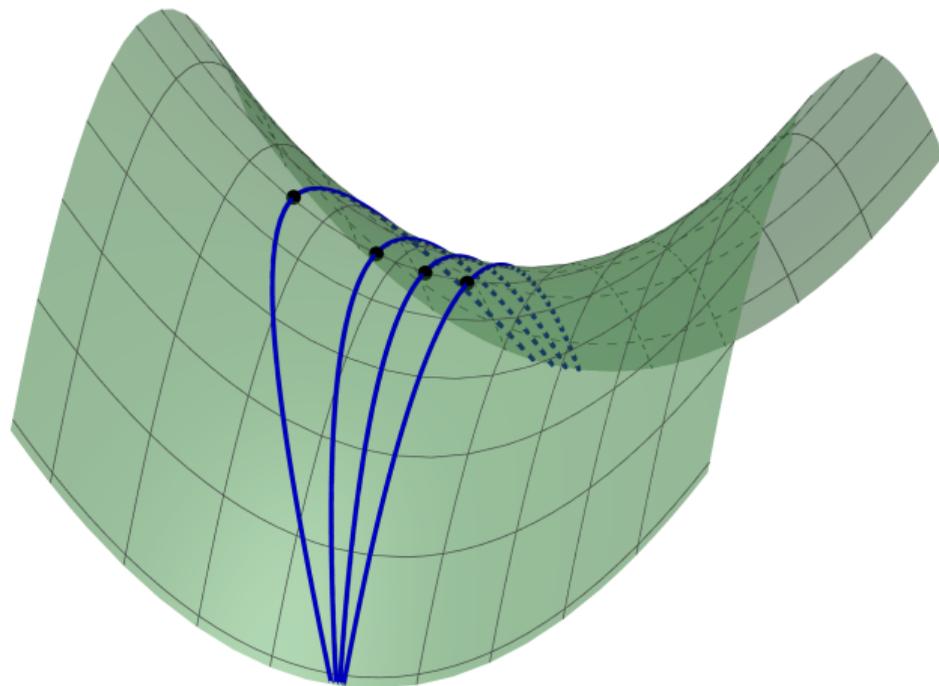
A sequence of **slices** $\{\Sigma_{t_n}^n\}$ is a **min-max sequence** if $\mathcal{H}^2(\Sigma_{t_n}^n) \rightarrow m_0(\Lambda)$.

To obtain minimal surfaces, we need to find a Λ such that $m_0(\Lambda) > 0$.









Constructing an appropriate saturated set

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Let $U_t = f^{-1}([0, t))$, $V_t = \psi(t, U_t)$. The volume $\text{Vol}(V_t)$ is continuous, and moreover $\text{Vol}(V_0) = 0$, $\text{Vol}(V_1) = \text{Vol}(M)$.

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In particular, there exists V_s whose volume is $\text{Vol}(M)/2$. By the isoperimetric inequality and by definition of $\mathcal{F}(\{\Gamma_t\})$,

$$0 < c(M) \leq \mathcal{H}^2(\Gamma_s) \leq \mathcal{F}(\{\Gamma_t\}),$$

and so $m_0(\Lambda) \geq c(M) > 0$.

Theorem [Simon-Smith]

Let M be a closed Riemannian 3-manifold. Given any saturated set Λ such that $m_0(\Lambda) > 0$, there exists a min-max sequence converging to a **embedded minimal surface** with area $m_0(\Lambda)$ (possibly with multiplicity).

Main Theorem

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We will find an appropriate min-max sequence converging to a **minimal surface**.

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Regular surfaces as linear operators

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Any surface $\Sigma \subset U$ with **finite area** induces a (non negative) bounded linear operator on $C_c(G(U))$:

$$\varphi(x, \pi) \in C_c(G(U)) \mapsto \int_{\Sigma} \varphi(x, T_x \Sigma) d\mathcal{H}^2$$

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Moreover, there exists a unique measure $\|V\|$, called the **mass measure**, defined on U , and such that given $\varphi \in C_c(U)$,

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If Σ is a surface and V_Σ is its associated varifold, then $\|V_\Sigma\|(U)$ is the area of Σ in U .

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is **metrizable** and **compact**. In particular, any sequence of varifolds with **uniformly bounded mass** has a **convergent subsequence**.

A varifold V is **rectifiable** if there is a set $S = \cup_{i \in \mathbb{N}} \Sigma_i$, where Σ_i are C^1 surfaces, and a Borel function $h : S \rightarrow [0, \infty)$ such that

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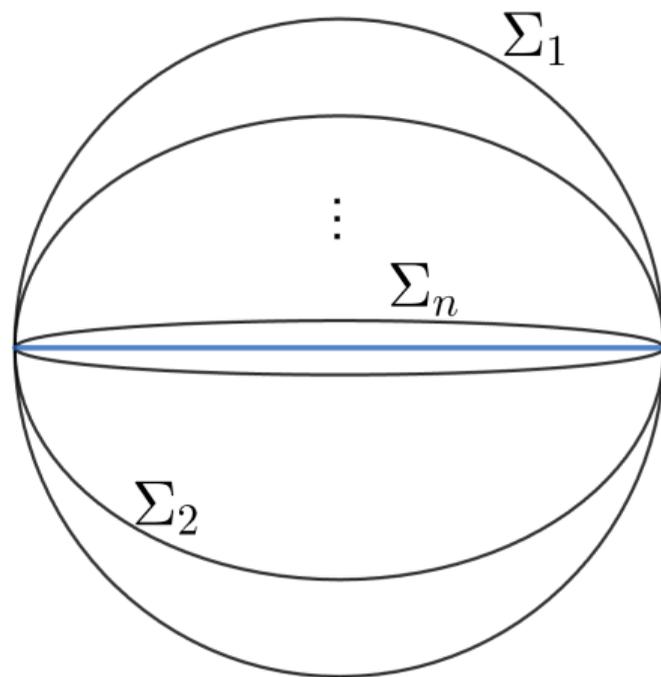
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Given $x \in M$, $V \in \mathcal{V}(U)$ and $\rho > 0$, let T_{ρ}^x be the dilation of factor ρ , and define $V_{\rho}^x := (T_{\rho}^x)_{\#} V$. Any limit $V' = \lim_{n \rightarrow \infty} V_{\rho_n}^x$ with $\rho_n \rightarrow \infty$ is a **tangent varifold** to V at x . We denote the set of all these limits by $T(x, V)$.

Some examples

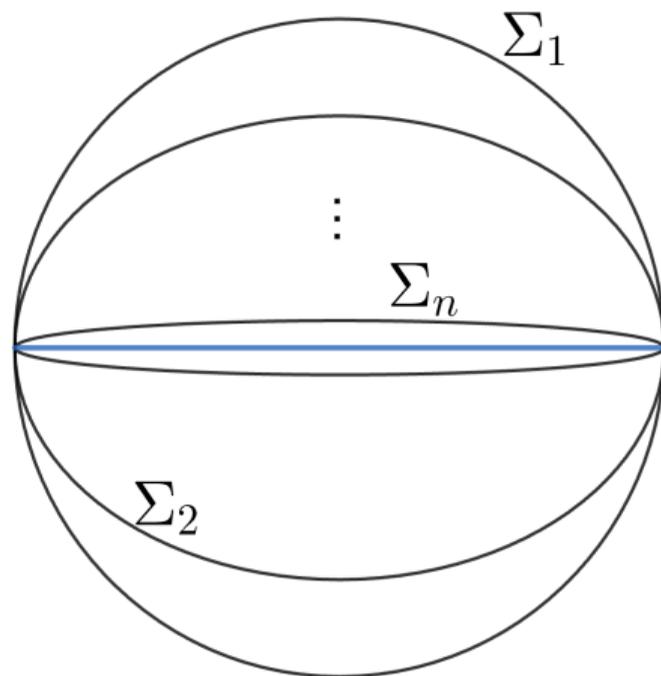
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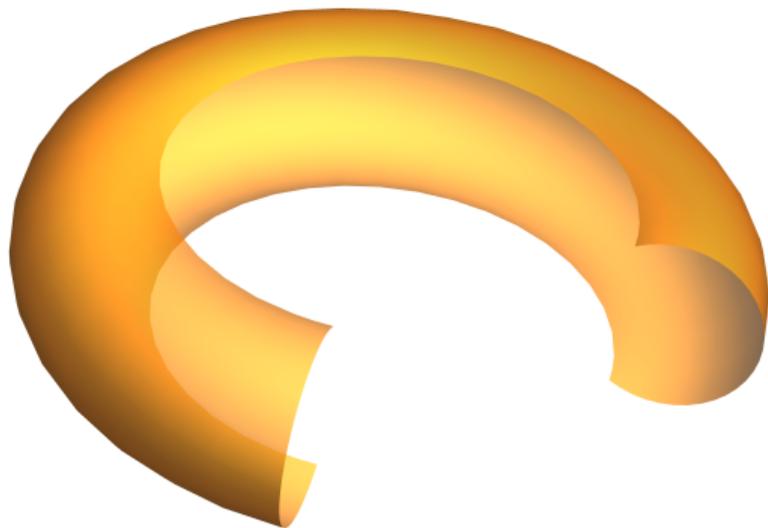


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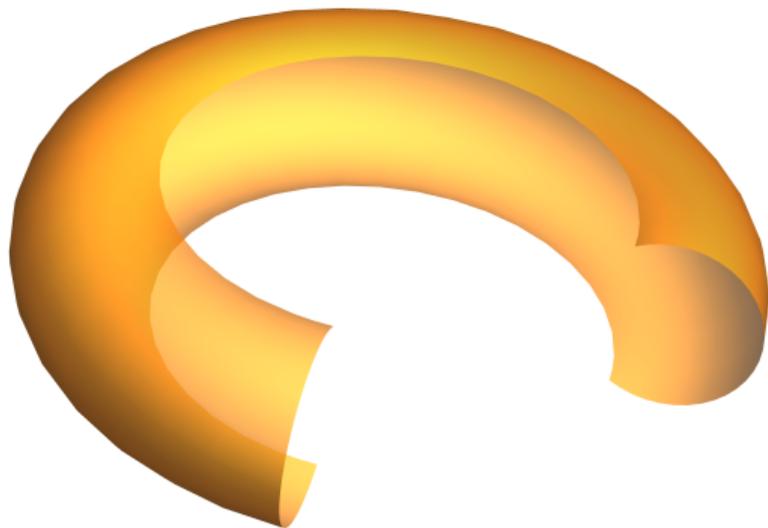
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In the limit, $\{\Sigma_n\}$ converge to a torus **with multiplicity 2**.



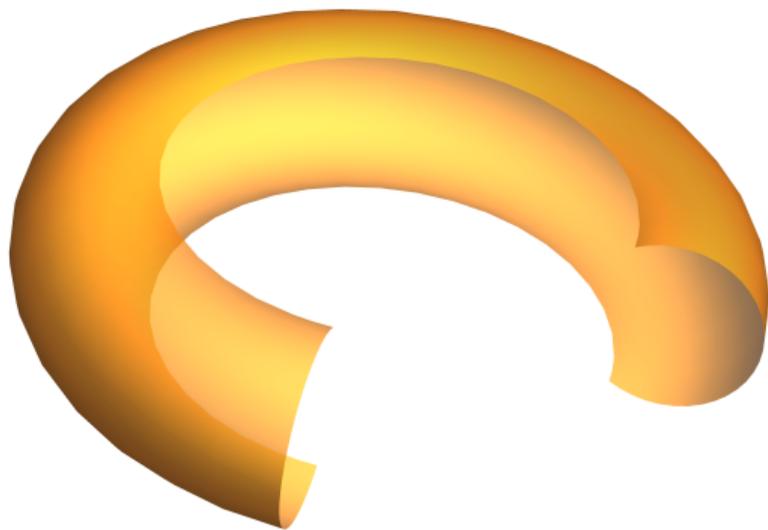
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In the limit, $\{\Sigma_n\}$ converge to a torus **with multiplicity 2**. In particular, **genus can be increased**.



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As measures on \mathbb{R}^2 , these segments converge to a horizontal segment with multiplicity $\sqrt{5}!$.

However, as **varifolds**, S_n converge to a **non-rectifiable** varifold.



First variation and stationary varifolds

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We define the **first variation** of a varifold V w.r.t. χ as

$$[\delta V](\chi) = \left. \frac{d}{dt} (\|\psi_\chi(t, \cdot)_\# V\|) \right|_{t=0} = \int_{G(U)} \operatorname{div}_\pi \chi dV(x, \pi).$$

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Stationary varifolds have several **key properties**:

- It is *not hard* for a stationary varifold to be **rectifiable**.
- They satisfy some minimal properties: monotonicity formula, a *maximum principle*...

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Theorem (Pull-tight process)

There exists a **minimizing sequence** $\{\Gamma_t\}^n$ such that **any** min-max sequence $\{\Gamma_{t_n}^n\}$ converges to a **stationary varifold**.

Idea of the Theorem: For each varifold we will define an isotopy $\psi_V(t, x)$ such that:

- If V is stationary, then $\psi_V(t, \cdot)$ is the **identity** map.
- Otherwise, $V' := (\psi_V(1, \cdot))_{\#} V$ has strictly less mass than V .
- The difference between $\|V'\|(M)$ and $\|V\|(M)$ depends **uniformly** on the distance between V and the set of stationary varifolds.

Pull-tight process

Let X be the set of varifolds with mass less or equal than $4m_0$, which is **compact** and **metrizable**.

Pull-tight process

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There exists $c = c(k) > 0$ such that, for each $V \in \mathcal{V}_k$ there exists χ_V with $\|\chi_V\| \leq 1$ and

$$[\delta V](\chi_V) \leq -c(k).$$

 \mathcal{V}_1

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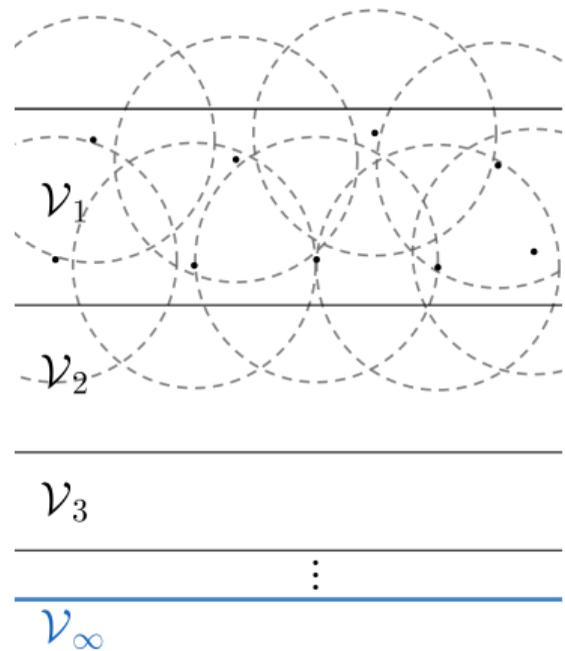
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By **compactness**, we can take a finite set of varifolds $V_i^k \subset \mathcal{V}_k$, fields χ_i^k and balls $B(V_i^k, r_i^k)$ s.t.:

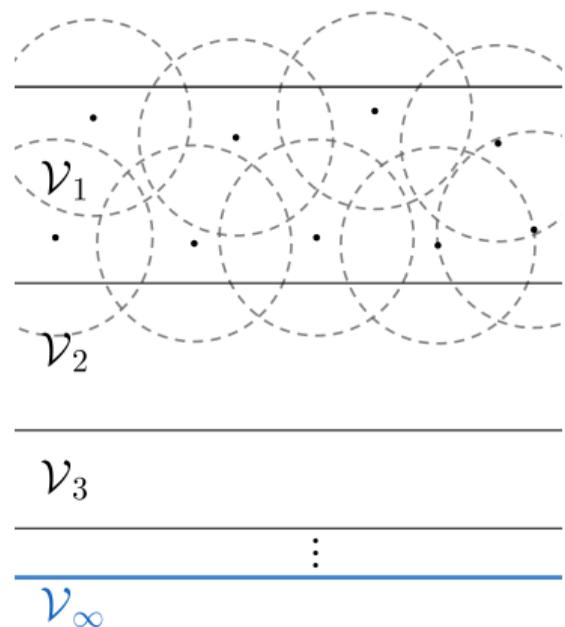
- If $V \in B(V_i^k, r_i^k)$, then $[\delta V](\chi_i^k) \leq -c(k)/2$.



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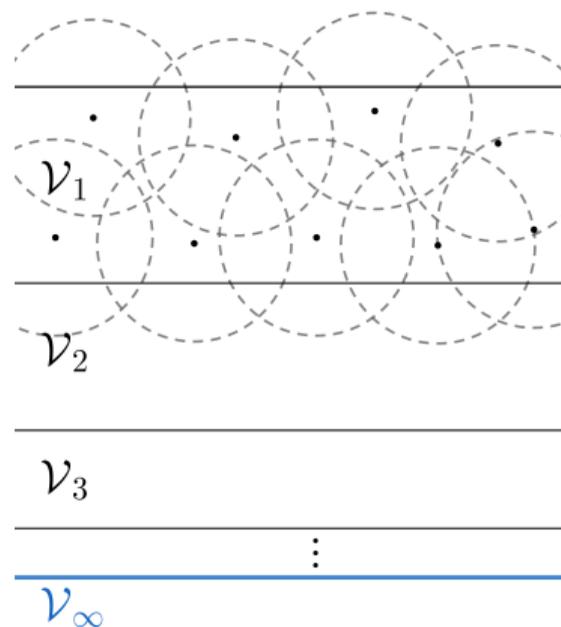
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Let $\varphi_i^k \in C_c(B(V_i^k, r_i^k/2))$ be a partition of the unit, and define $H : X \rightarrow C^\infty(M, TM)$ as

$$H(V) := \sum_{i,k} \varphi_i^k(V) \chi_i^k.$$

Notice that H is **continuous**.

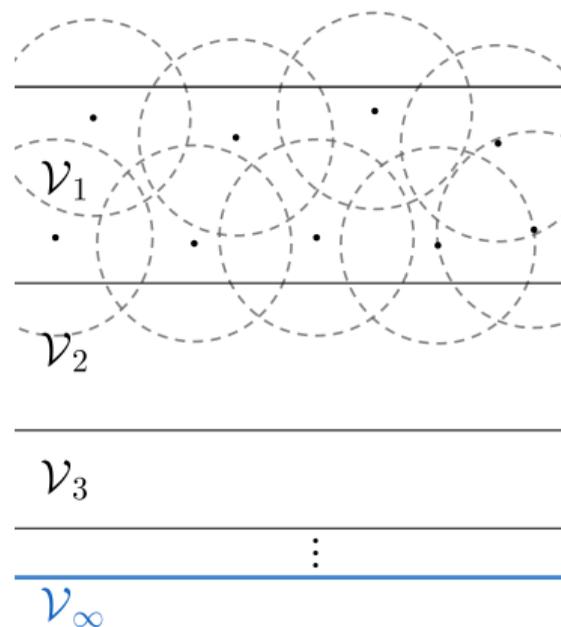


Pull-tight process

There exist constants $C = C(k)$ and a time $T = T(k)$ such that

$$\|V(T)\|(M) \leq \|V(0)\|(M) - C(k)$$

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Now, let $\{\Sigma_t\}^n$ be a minimizing sequence. Then, we can define a *tighter* minimizing sequence:

Let $\Gamma_t^n := \Sigma_t^n(T)$. Then, the sequence $\{\Gamma_t\}^n$ is minimizing and each min-max sequence converges to a **stationary varifold**.

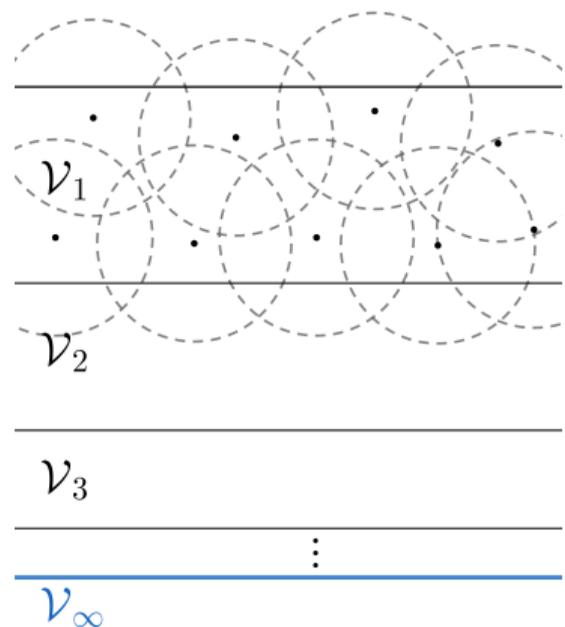


Table of Contents

- 1 Statement of the main Theorem
- 2 An (unfortunately irreducible) introduction to varifolds
- 3 Finding stationary varifolds
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 - Theorem 1: GRP implies minimality
 - Theorem 2: Existence of a.m. min-max sequence
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Almost minimizing surfaces

Let $\varepsilon > 0$, $U \subset M$ and $\Sigma \subset U$. We will say that the surface Σ is ε -almost minimizing if there **does not** exist any isotopy ψ supported in U such that:

- $\mathcal{H}^2(\psi(1, \Sigma)) \leq \mathcal{H}^2(\Sigma) - \varepsilon$.
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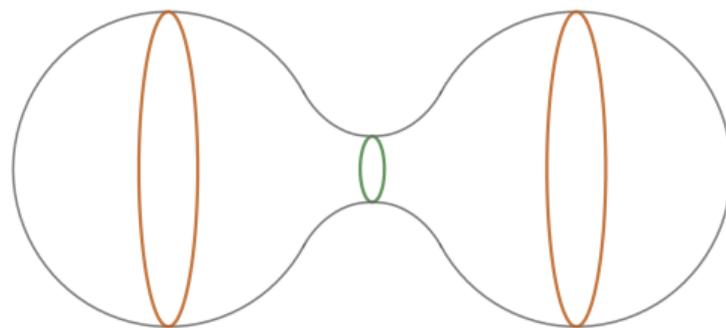
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Let $\mathcal{AN}(x, r)$ be the set of annuli centered in $x \in M$ with *outer radius* less than r .

A sequence $\{\Sigma^n\}$ is almost minimizing in small annuli if there exists $r : M \rightarrow (0, \infty)$ such that $\{\Sigma^n\}$ is almost minimizing in every $A_n \in \mathcal{AN}(x, r(x))$.

An example

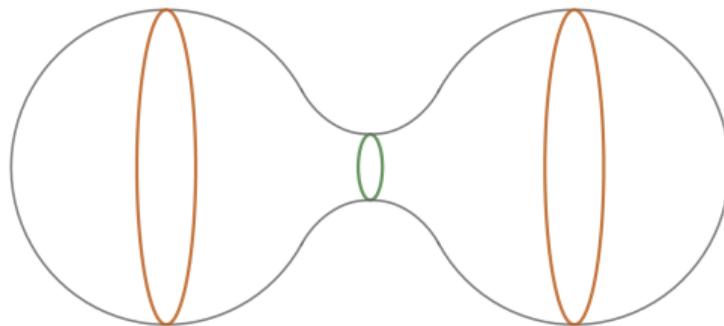
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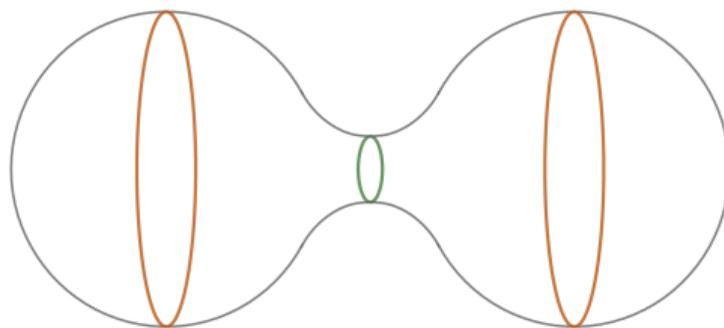


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However, the geodesic in the middle is **almost minimizing**: in order to decrease its length, one must increase it first.



Why minimizing on annuli?

It is natural to ask why we consider minimization on annuli rather than balls. There are two reasons for it:

- **Singularities:** our initial surfaces present point singularities. We can *isolate* them by using [annuli](#).

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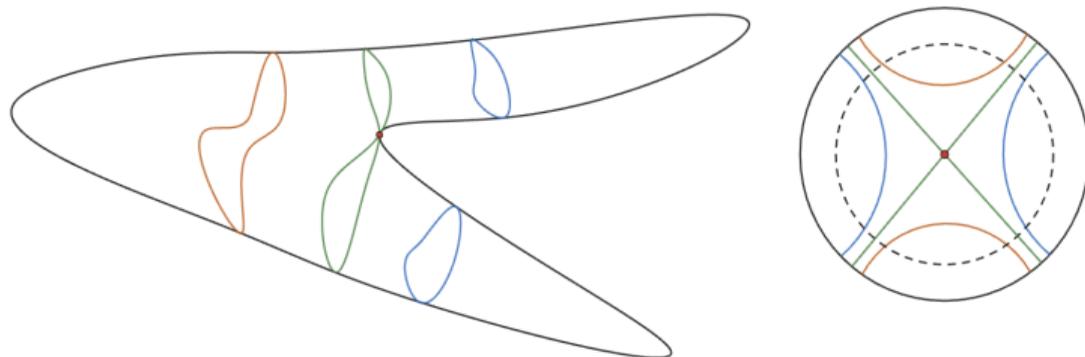
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Replacements

Let V be a **stationary** varifold and $U \subset M$. We say that V' is a **replacement** of V in U if:

- V' is **stationary** and $\|V\| = \|V'\|$.
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We say that V has the **good replacement property** if:

- V has a replacement V' in any $A_n \in \mathcal{AN}(x, r(x))$.
- V' has a second replacement V'' in any $A_n \in \mathcal{AN}(y, r(y))$.
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Theorem 3 (a.m. min-max sequence has GRP)

The varifold V of the previous Proposition has the good replacement property. In particular, V is an **embedded, minimal surface** with area $m_0(\Lambda)$.

Talk structure

- 1 Statement of the main Theorem
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Given a **stationary** varifold V , assume that $\theta(x, V) > 0$ $\|V\|$ -a.e. where $\theta(x, V) = \lim_{r \rightarrow 0} f_x^V(r)$. Then, V is **rectifiable**. [GMT, Theorem 8.1.2.]

Now we prove that V is **integer** rectifiable:

Let V be a stationary rectifiable varifold with $\theta(x, V) \geq c > 0$ for all $x \in M$. Then, any tangent varifold is a **Euclidean stationary rectifiable cone**. [GMT, Corollary 8.5.7]

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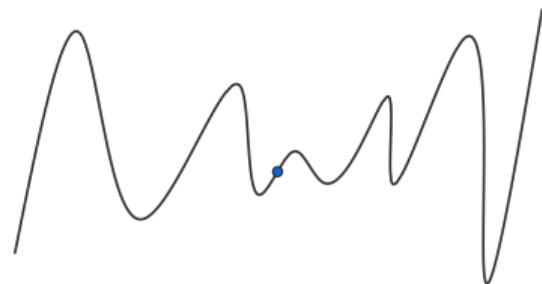
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Schoen's curvature estimate

If $\{\Sigma^n\}$ is a sequence of stable minimal surfaces in $U \subsetneq M$, then a subsequence converges to a stable minimal surface Σ .

Replacements of V

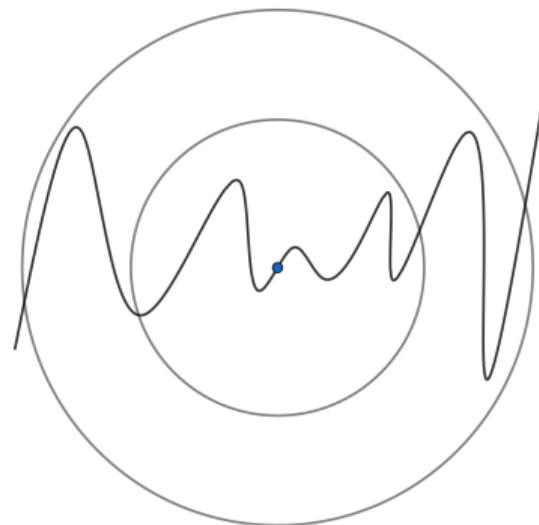
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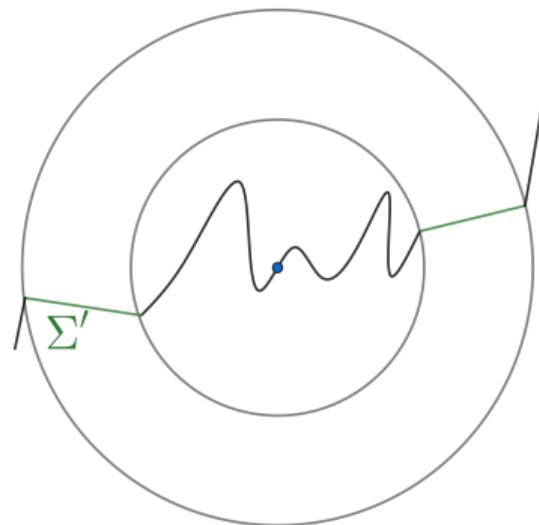


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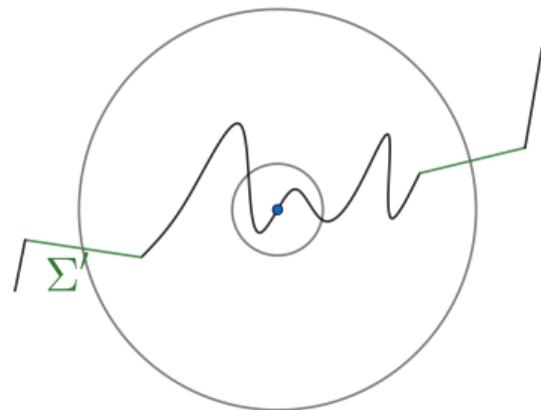
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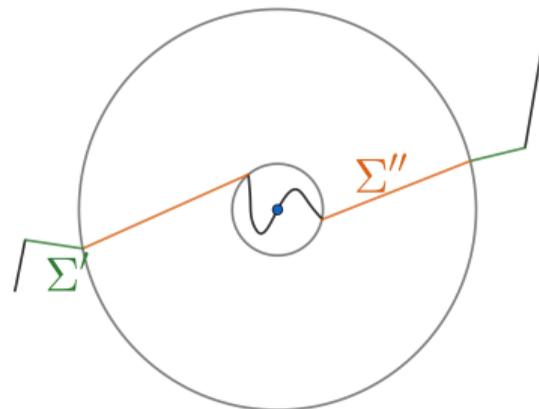
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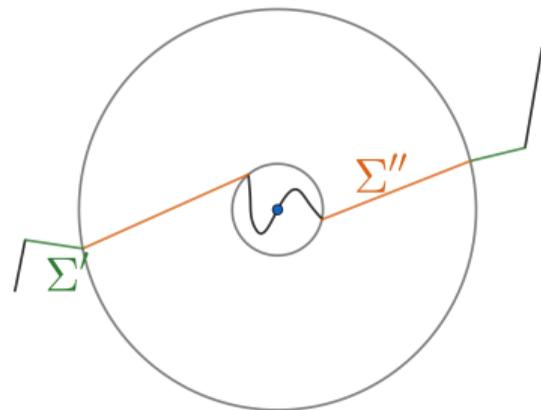
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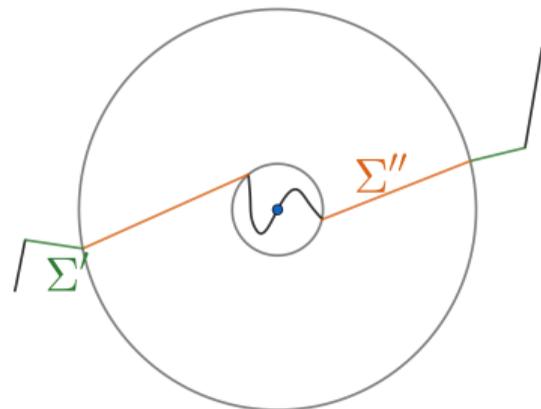
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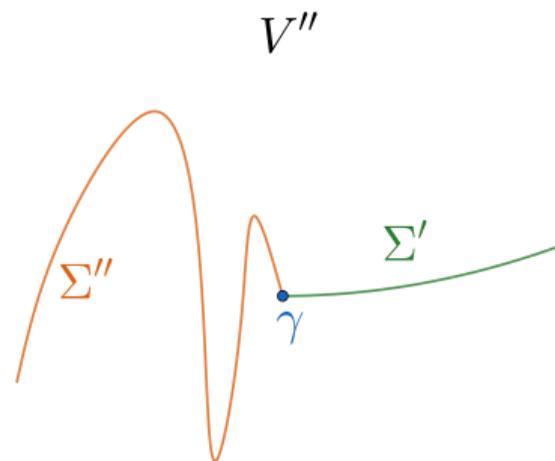
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We have two surfaces Σ' and Σ'' . **Do they coincide?**



Gluing two minimal surfaces

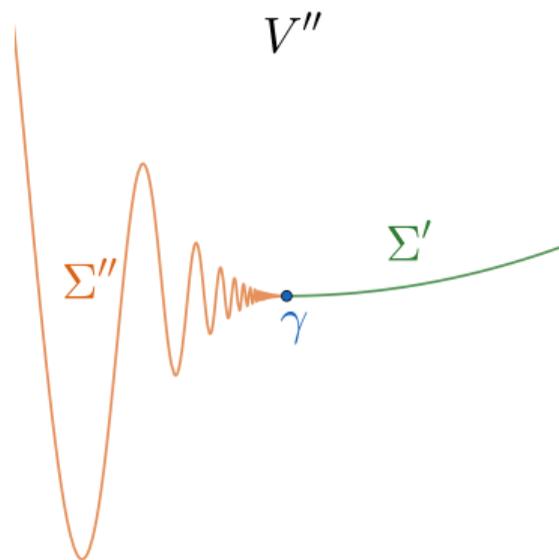
Let $\gamma := \Sigma' \cap \partial B_t$, and take t so that Σ' meets ∂B_t transversally. One can check that V'' has a tangent plane along γ , which must coincide with that of Σ' .



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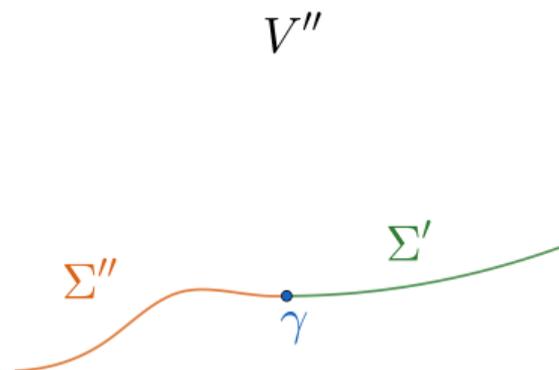


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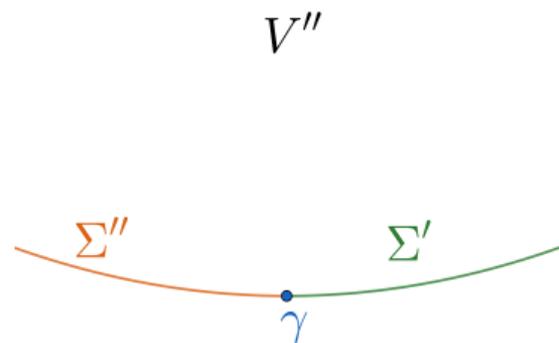
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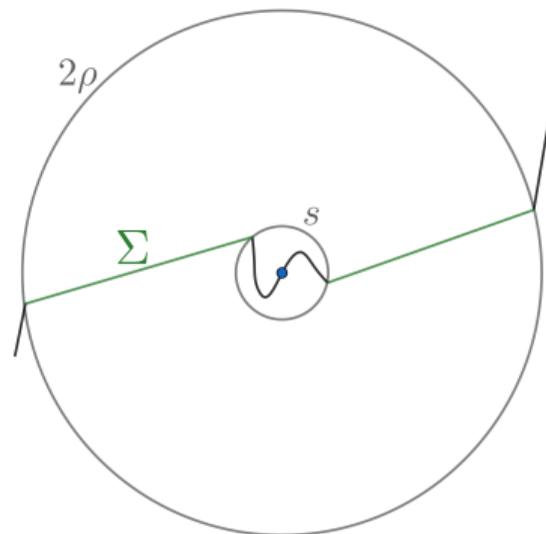
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By PDE theory, since Σ' , Σ'' and their Gauss maps coincide along γ , $\Sigma' \equiv \Sigma''$.



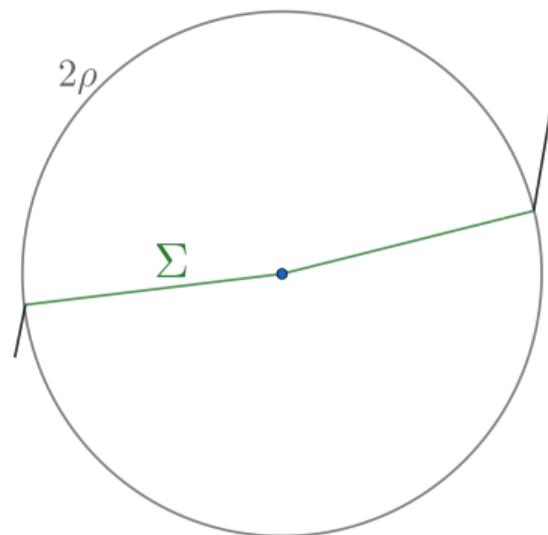
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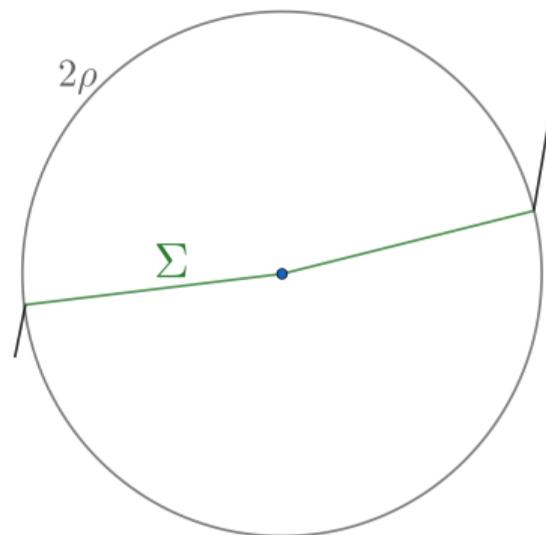


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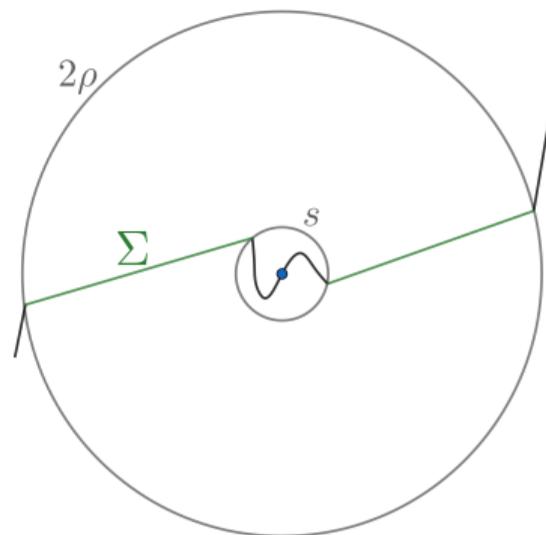
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Proof: First, notice that V and V'' are **integer rectifiable**.



Extending Σ

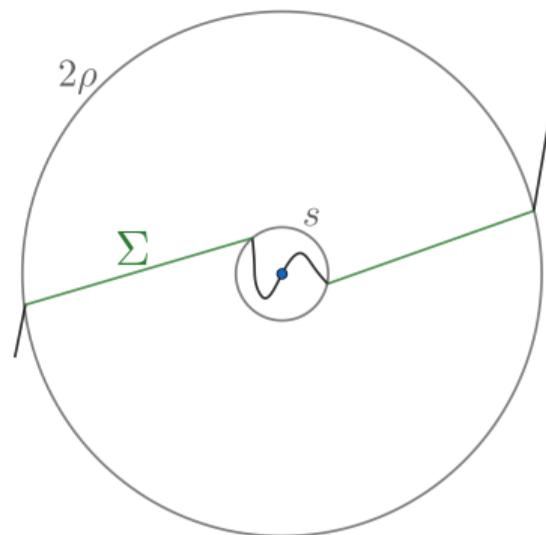
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Σ coincides with V in $B^*(x, \rho)$. More specifically,

$$\text{Supp}(\|V\|) \cap B^*(x, \rho) = \Sigma \cap B^*(x, \rho)$$

Proof: First, notice that V and V'' are **integer rectifiable**.

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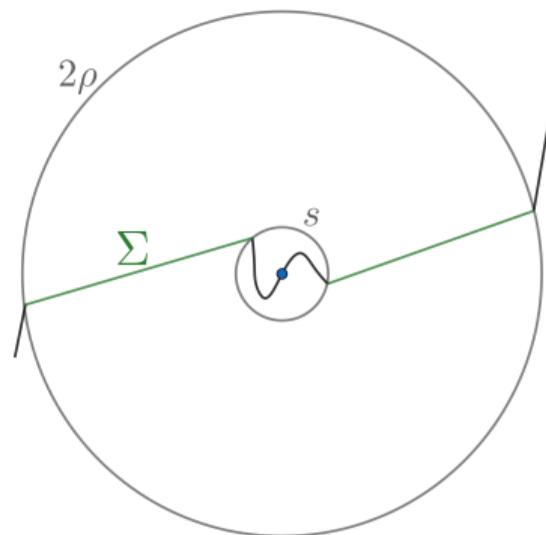
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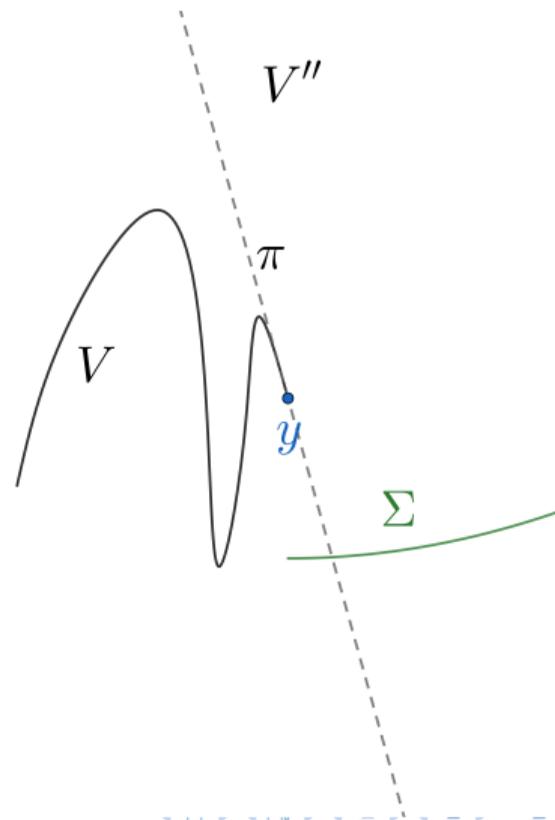
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Let $y \in \text{Supp}(\|V\|) \cap B^*(x, \rho)$ s.t. V meets $\partial B(x, s)$ **transversally**, where $s := d(x, y)$. In particular, there exists a plane $\pi \in T_y M$ tangent to V .



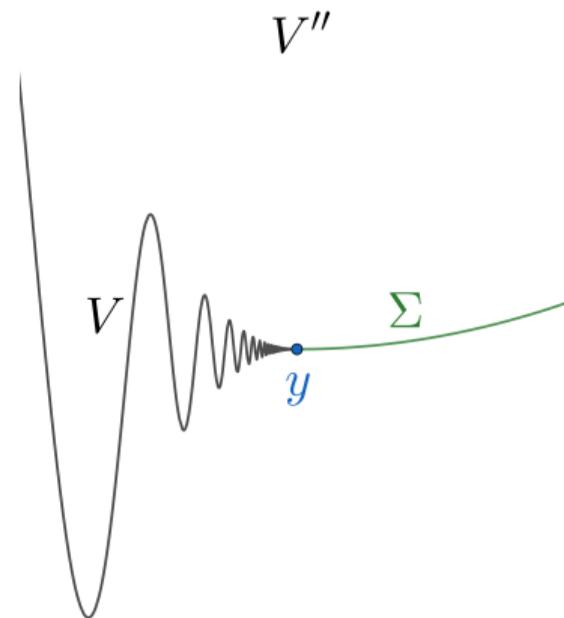
$V = \Sigma$ on a punctured ball

Since $V = V''$ in $B(x, s)$, π is tangent to V'' .



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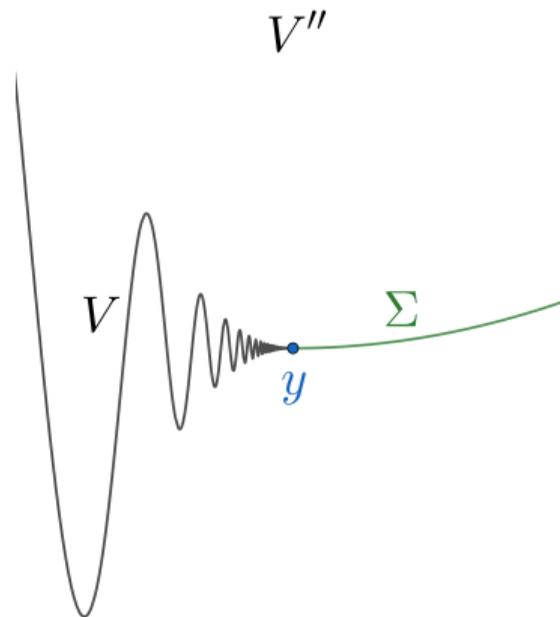
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As a result, $y \in \Sigma$.

The set of points $y \in \text{Supp}(\|V\|) \cap B^*(x, \rho)$ transversal to $\partial B(x, s)$ is **dense**.



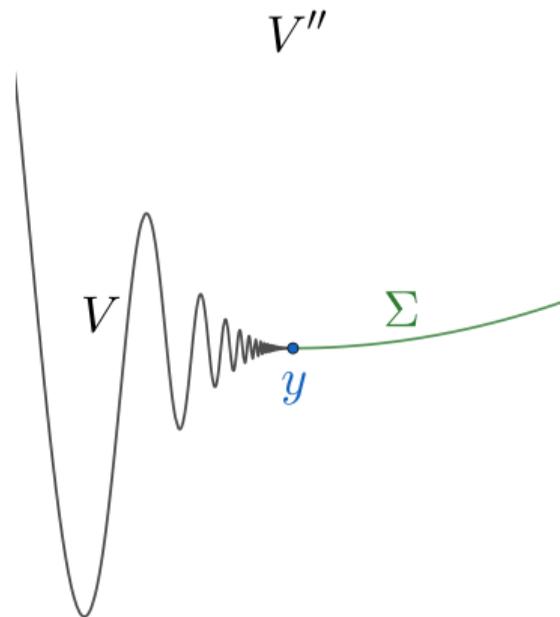
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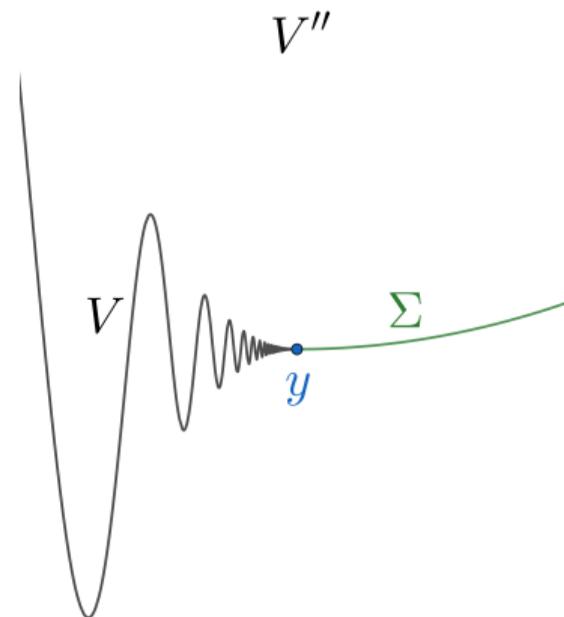
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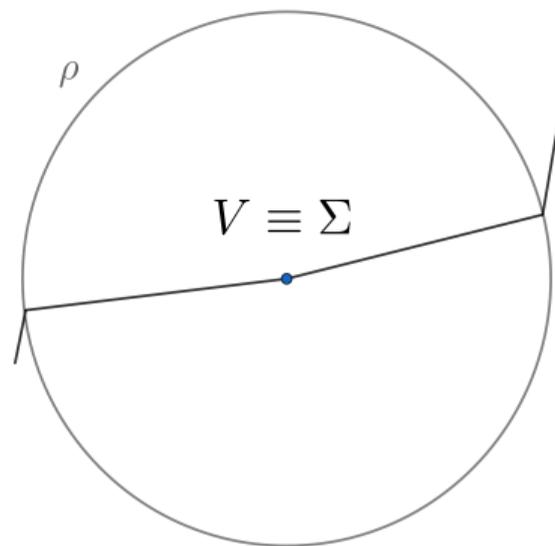
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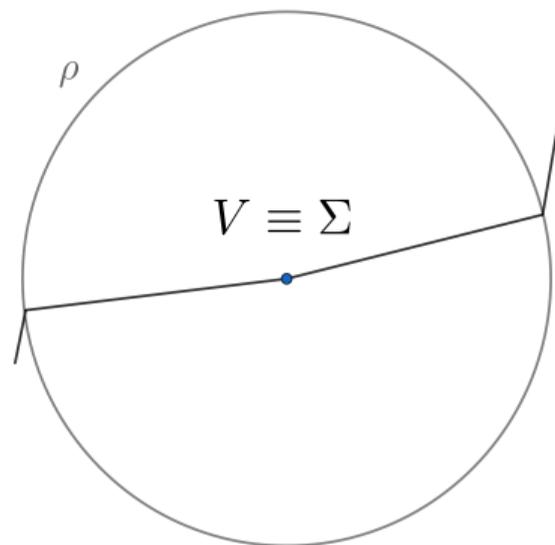
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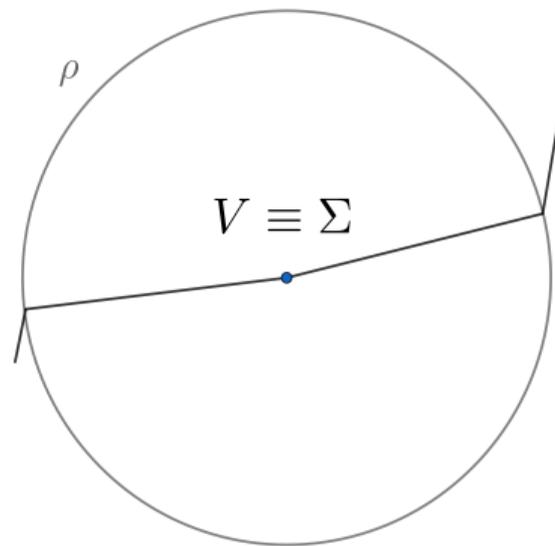
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As a result, $V|_{B^*(x, \rho)} = \Sigma$. Now, can we extend Σ smoothly to x ?



Smooth extension of Σ at x

We know that the tangent varifold to V at x is a **plane** π with multiplicity M .



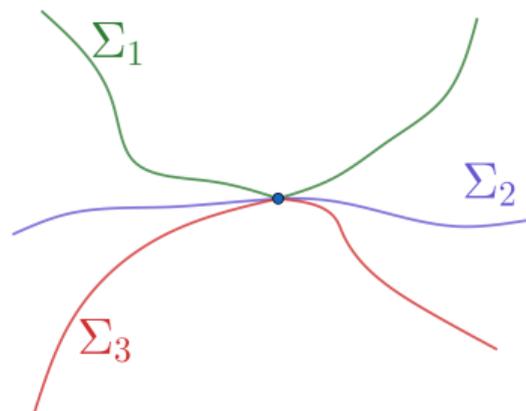
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Stability shows that near x , there are minimal Lipschitz graphs Σ_i and constants m_i , $1 \leq i \leq N$ with $\sum m_i = M$ and

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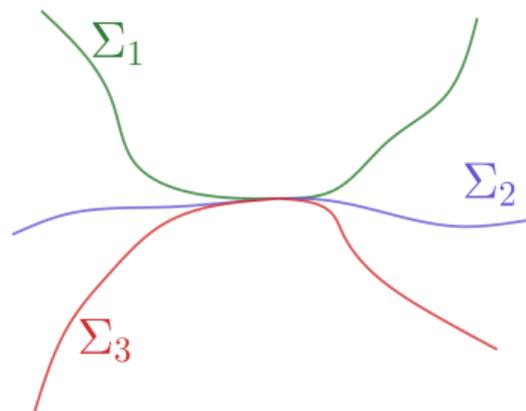
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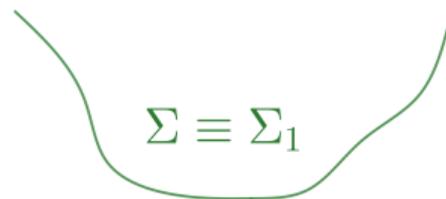
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near x . Moreover, Σ_i are **ordered by height**.

By **Allard's regularity Theorem**, each Σ_i extends smoothly to x . By the maximum principle, $N = 1$, and Σ is **embedded**.



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- 4 Regularity analysis of limit varifolds**
 - Theorem 1: GRP implies minimality
 - Theorem 2: Existence of a.m. min-max sequence**
 - Theorem 3: a.m. min-max sequence has GRP
- 5 Generalizations of the main Theorem

Regularity results

Theorem 1 (GRP implies minimality)

If V has the good replacement property, then it is an **embedded minimal surface**.

Theorem 2 (Existence of a.m. min-max sequence)

There exists a min-max sequence $\{\Sigma^n\}$ which is **almost minimizing** in small annuli and converges to a **stationary varifold** V . Moreover, given any small annulus A_n , $\Sigma^n|_{A_n}$ is a **smooth surface** for sufficiently large n .

Theorem 3 (a.m. min-max sequence has GRP)

The varifold V of the previous Proposition has the good replacement property. In particular, V is an **embedded, minimal surface** with area $m_0(\Lambda)$.

Sketch of the proof

We need to prove that there exists a **min-max sequence** $\{\Sigma^n\}$ s.t.:

- 1 It converges to a stationary varifold,
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Finding an almost minimizing min-max sequence

Let \mathcal{CO} be the set of pairs (U_1, U_2) such that

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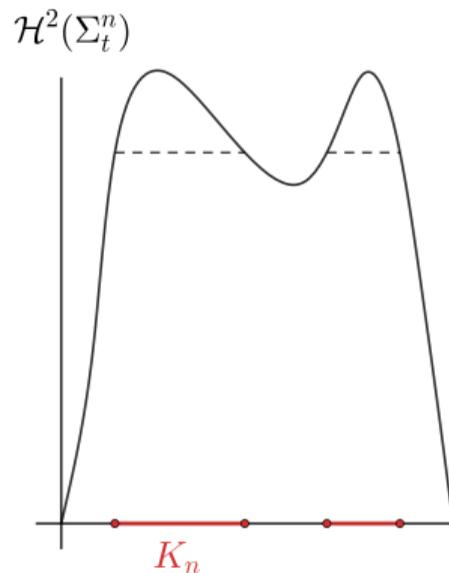
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In any of the cases, we obtain a min max subsequence $\{\Sigma^{L(j)}\}$ which is a.m. in small annuli.

Proof of the Proposition

Let $L \in \mathbb{N}$, and

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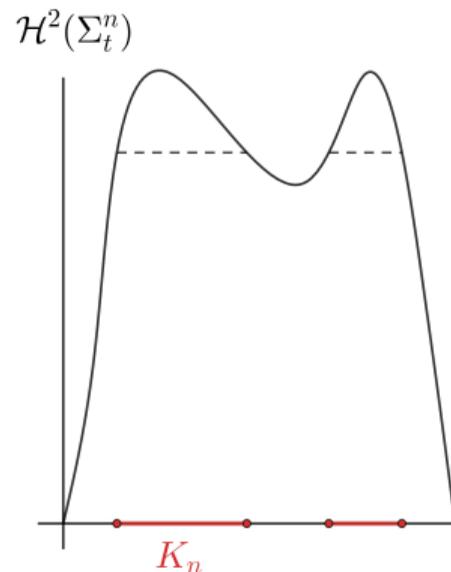


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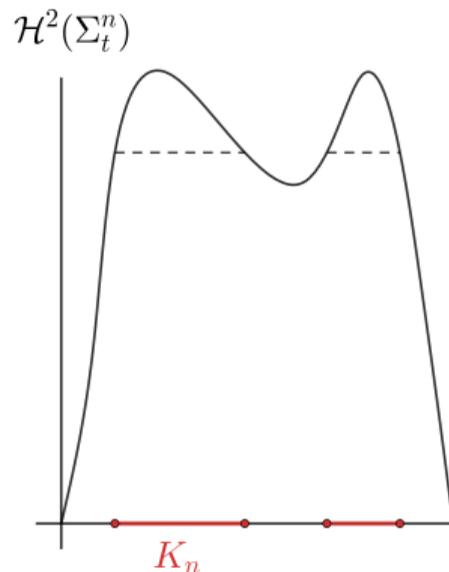


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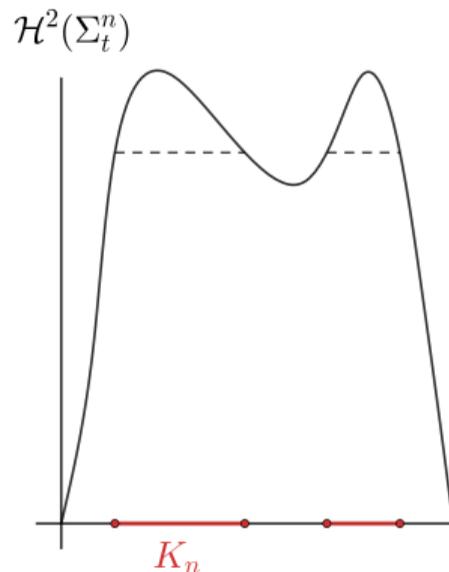
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We can find **at least** two isotopies ψ_U and ψ_V which **decrease** the area of Σ_t^n with **small increase in the process**.



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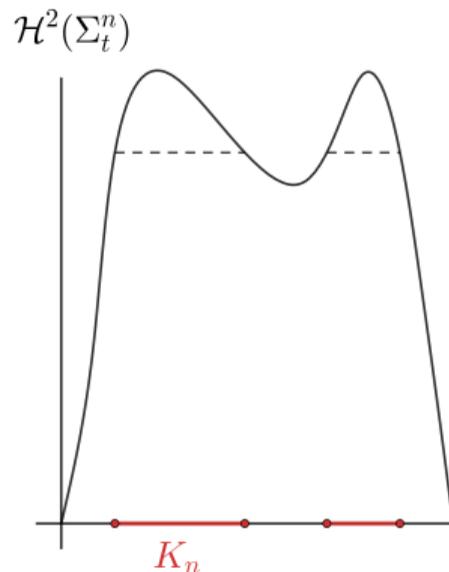
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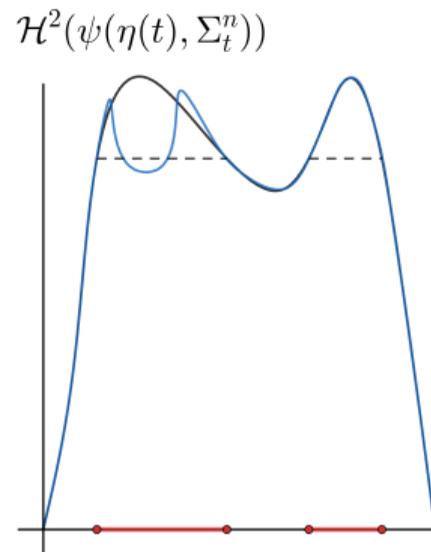
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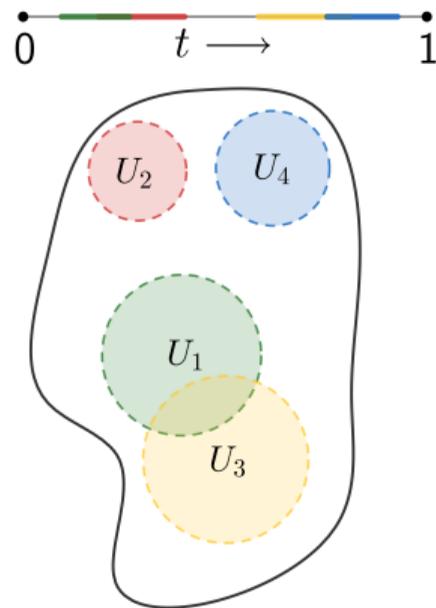
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Idea: apply one of the isotopies ψ_U, ψ_V **along** I .



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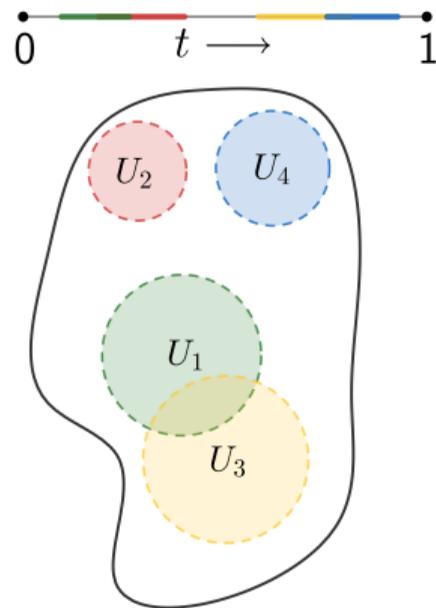
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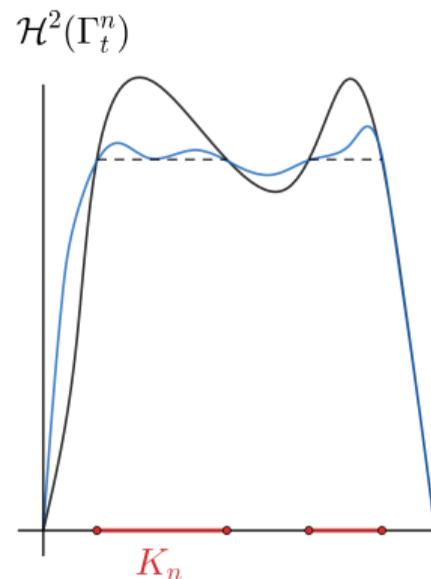
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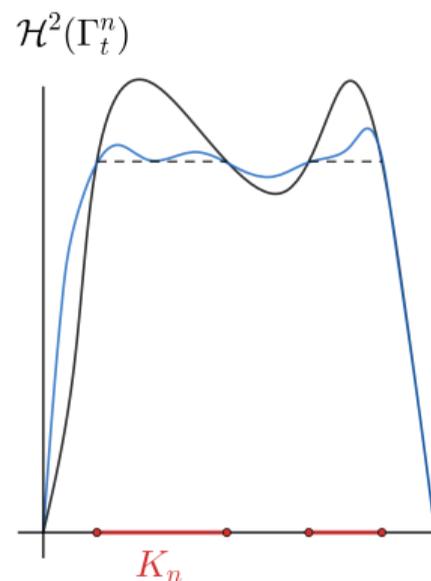
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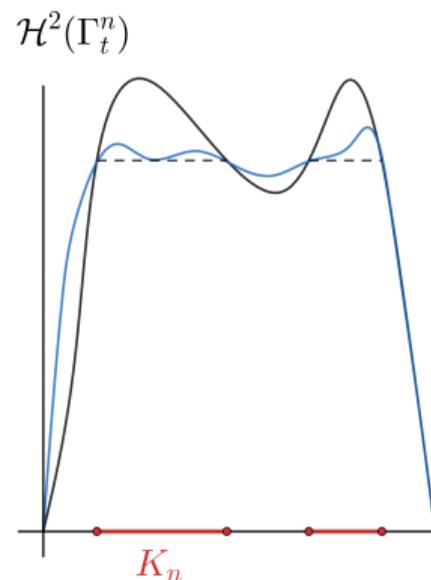
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In particular, $\lim_n \mathcal{F}(\{\Gamma_t^n\}) \leq m_0(\Lambda) - 1/2L!!$



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Theorem 3 (a.m. min-max sequence has GRP)

The varifold V of the previous Proposition has the good replacement property. In particular, V is an **embedded, minimal surface** with area $m_0(\Lambda)$.

Preliminary definitions and results

Let \mathcal{I} be a set of **smooth isotopies** on M and Σ be a surface. We say that $\{\psi^k(1, \Sigma)\} \subset \mathcal{I}$ is **minimizing** for (Σ, \mathcal{I}) if

$$\lim_k \mathcal{H}^2(\psi^k(1, \Sigma)) = \inf_{\psi \in \mathcal{I}} \mathcal{H}^2(\psi(1, \Sigma)).$$

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Given $U \subset M$ and an **embedded** surface Σ , we define:

- $\mathfrak{I}\mathfrak{s}(U)$: the set of all smooth isotopies supported in U .
- $\mathfrak{I}\mathfrak{s}_j(U) := \{\psi \in \mathfrak{I}\mathfrak{s}(U) : \mathcal{H}^2(\psi(t, \Sigma)) \leq \mathcal{H}^2(\Sigma) + \frac{1}{8j}\}$.

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Theorem (Meeks-Simon-Yau)

Let $\{\Sigma^k\} \subset \mathfrak{I}\mathfrak{s}(U)$ be **minimizing** and converging to a varifold V . Then, $V|_U$ is an **stable, embedded, minimal surface**.

Proof of Theorem 3

Let $\{\Sigma^j\}$ be the a.m. min-max sequence obtained in Theorem 2, which converges to a stationary varifold V .

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Any limit V^* of a subsequence of $\{V^j\}$ is a **replacement** for V in A_n .

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We assume **Lemma B**:

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- V^* is **stationary**: Otherwise, one can prove that Σ^j cannot be $1/j$ -almost minimizing for j big enough.

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Fix j , and let $V' := V^j$ be the limit of $\Sigma^k := \Sigma^{j,k}$. We want to prove that $V'|_{A_n}$ is a stable, embedded, minimal surface. The proof is based on **Lemma A**:

Let $x \in A_n$ and k large enough. There exists $\varepsilon > 0$ s.t. any isotopy $\varphi \in \mathcal{I}\mathfrak{s}(B_\varepsilon(x))$ can be achieved via an isotopy $\Phi \in \mathcal{I}\mathfrak{s}_j(B_{2\varepsilon}(x))$.

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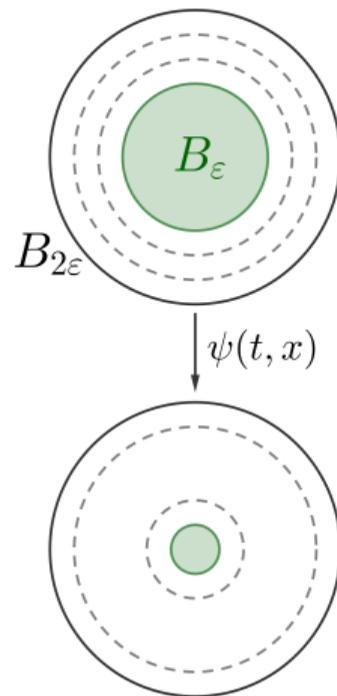
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Proof: Let $\psi(t, x)$ be an isotopy which *squeezes* the ball $B_\varepsilon(x)$ in $B_{2\varepsilon}(x)$ with scale factor $(1 - t)$.



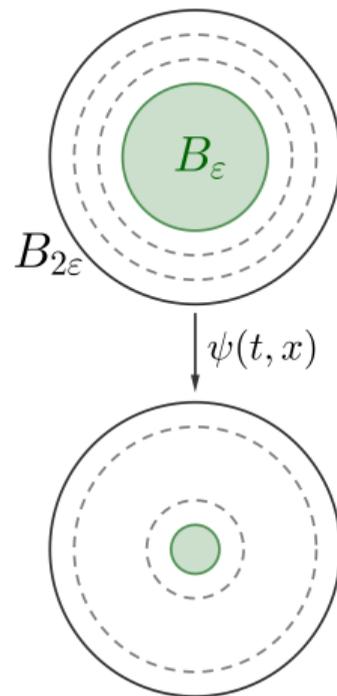
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Proof: Let $\psi(t, x)$ be an isotopy which *squeezes* the ball $B_\varepsilon(x)$ in $B_{2\varepsilon}(x)$ with scale factor $(1 - t)$.

For large enough k , we can find a certain $\psi(t, x)$ satisfying

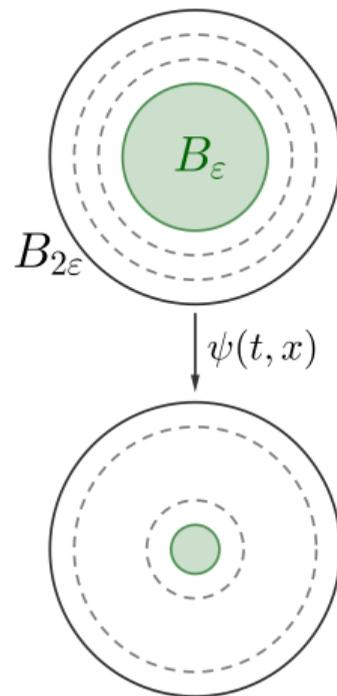
$$\mathcal{H}^2(\psi(t, \Sigma^k)) \leq \mathcal{H}^2(\Sigma^k) + C\varepsilon^2.$$



Proof of Lemma A

Now, given $\varphi \in \mathfrak{I}\mathfrak{s}(B_\varepsilon(x))$, let Φ be the isotopy which applies this process:

- First, it *squeezes* B_ε via $\psi(t, x)$ up to a certain factor $(1 - t_0)$.
- Then, it applies the isotopy φ on the *squeezed ball* $B_{(1-t_0)\varepsilon}(x)$.
- Finally, it *enlarges* $B_\varepsilon(x)$ by applying $\psi(t, x)$ *reversely*.

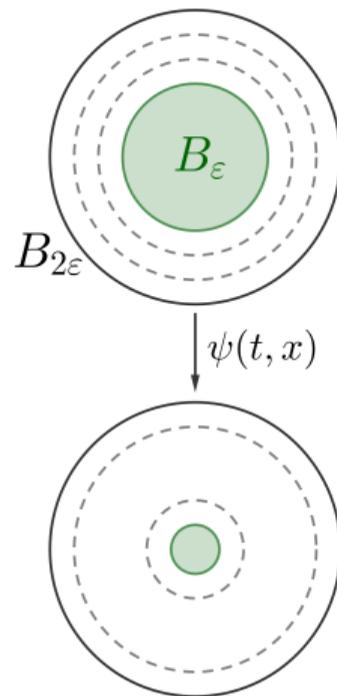


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Now, given $\varphi \in \mathfrak{Is}(B_\varepsilon(x))$, let Φ be the isotopy which applies this process:

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- Finally, it *enlarges* $B_\varepsilon(x)$ by applying $\psi(t, x)$ *reversely*.

$\varphi(1, x) \equiv \Phi(1, x)$. Moreover, if t_0 is sufficiently close to 1, $\Phi(t, x) \in \mathfrak{Is}_j(B_{2\varepsilon}(x))$.



Regularity results

Theorem 1 (GRP implies minimality)

If V has the good replacement property, then it is an **embedded minimal surface**.

Theorem 2 (Existence of a.m. min-max sequence)

There exists a min-max sequence $\{\Sigma^n\}$ which is **almost minimizing** in small annuli and converges to a **stationary varifold** V . Moreover, given any small annulus A_n , $\Sigma^n|_{A_n}$ is a **smooth surface** for sufficiently large n .

Theorem 3 (a.m. min-max sequence has GRP)

The varifold V of the previous Proposition has the good replacement property. In particular, V is an **embedded, minimal surface** with area $m_0(\Lambda)$.

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- 3 Finding stationary varifolds
- 4 Regularity analysis of limit varifolds
 - Theorem 1: GRP implies minimality
 - Theorem 2: Existence of a.m. min-max sequence
 - Theorem 3: a.m. min-max sequence has GRP
- 5 Generalizations of the main Theorem

A **Heegaard surface** in a compact oriented manifold M is a closed orientable surface such that $M \setminus \Sigma$ consists of two open **genus g** handlebodies.

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A **Heegaard sweepout** is a family $\{\Sigma_t\}_{t \in [0,1]}$ of closed subsets of M such that:

- $t \mapsto \Sigma_t$ is continuous in the Hausdorff topology.
- For $t \in (0, 1)$, Σ_t is a smooth Heegaard surface.
- Σ_t varies smoothly for $t \in (0, 1)$.
- Σ_0 and Σ_1 are 1-d graphs which correspond to the spines of the handlebodies determined by the Heegaard surfaces.

Theorem (Ketover)

Let M be a oriented 3-manifold admitting a **genus g** Heegaard surface. Then, there exists some min-max sequence $\{\Sigma^j\}$ converging as varifolds to $\Gamma := \sum_j n_j \Gamma_j$, where Γ_j are pairwise disjoint, embedded, minimal surfaces. Moreover, it holds

$$\sum_{i \in O} n_i g(\Gamma_i) + \frac{1}{2} \sum_{i \in N} n_i (g(\Gamma_i) - 1) \leq g,$$

where O (resp. N) is the set of orientable (resp. non-orientable) surfaces.

Genus bounds in Simon-Smith min-max theory

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As a direct corollary,

Theorem (Simon-Smith)

Every **3-sphere** admits an embedded, minimal **2-sphere**.

Equivariant min-max theory

Suppose M admits a finite **isometry group** G . Does there exist a G -equivariant minimal surface?

Equivariant min-max theory

Suppose M admits a finite **isometry group** G . Does there exist a G -equivariant minimal surface?

If G is **free**, then the quotient M/G is a **compact manifold**.

Equivariant min-max theory

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Let G be a **finite, orientation-preserving** isometry group and $x \in M$. We define the **isotropy subgroup** G_x of x as

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\mathcal{S} can be expressed as a graph $\mathcal{S} := \mathcal{S}_0 \sqcup \mathcal{S}_1$, where \mathcal{S}_1 are **geodesics** whose endpoints belong to \mathcal{S}_0 .

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Let M be a closed oriented 3-manifold and G be a finite group of orientation-preserving isometries on M . Given a G -sweepout by surfaces of genus g , there exists an **embedded, minimal** G -equivariant surface $\Gamma = \sum_j n_j \Gamma_j$.

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Moreover, the following properties hold:

- The same genus bounds as in the previous Theorem.
- If $x \in \mathcal{S}_1 \cap \Gamma$ and $G_x \neq \mathbb{Z}_2$, then Γ intersects \mathcal{S}_1 **orthogonally** at x .
- If, however, $G_x = \mathbb{Z}_2$, the intersection may also be tangent. In that case, Γ contains the geodesic of constant isotropy passing through x .
- Γ can only intersect \mathcal{S}_0 at a point with isotropy group \mathbb{D}_n . In that case, Γ contains $2n$ arcs of isotropy \mathbb{Z}_2 .

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Let \mathbb{B}^3 be the unit ball in Euclidean space. Given a G -sweepout by genus g surfaces, there exists a **free boundary, embedded, minimal** surface Γ **with multiplicity n** .

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What can we say about the boundary components of Γ ?

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Let us assume that ∂M is **mean-convex**. Then,

Theorem (Franz, Schulz)

Given a G -sweepout by genus g (orientable) surfaces with b boundary components, there exists a **free boundary, embedded, minimal** surface $\Gamma = \sum_j n_j \Gamma_j$.

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$$\sum_{i \in \mathcal{O}} g(\Gamma_i) + \frac{1}{2} \sum_{i \in \mathcal{N}} (g(\Gamma_i) - 1) \leq g$$

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Regarding the boundary complexity $\mathfrak{b} := b - 1$,

$$g(\Gamma) + \mathfrak{b}(\Gamma) \leq g + \mathfrak{b}.$$

A general existence theorem

Given an open subset $\Omega \subset M$, let us consider the functional

$$\mathcal{A}(\Omega) := \mathcal{H}^2(\partial\Omega_1) + \cos(\theta)\mathcal{H}^2(\partial\Omega_2) - c\text{Vol}(\Omega),$$

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In general, critical points of \mathcal{A} are **capillary, CMC** surfaces with $H \equiv c$ and contact angle θ .

Theorem (Li, Zhou, Zhu)

Given any closed oriented manifold M with smooth boundary, $c \geq 0$ and $\theta \in (0, \pi/2]$, there exists a **capillary, CMC, almost embedded** surface with contact angle θ and $H \equiv c$.

Note: No genus or boundary component bounds are known for this case.

Thank you for your attention!

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